

AMENDMENTS TO THE CLAIMS

This listing of claims will replace all prior versions, and listings, of claims in the application:

Listing of Claims:

1. (Currently Amended) A ~~procedure~~process for ~~determining the determination of~~ the magnitude of a noise (T_{DUT}) of an electronic object to be measured, said process comprising:
~~(2) by the inputting of a sine signal (S_{in}) into the electronic object; and the measurement~~
measuring of an associated power level by means of with a level meter, wherein the level
~~meter determines (3), therein characterized, in that by means of the level meter (3), a sine~~
power level (\hat{P}_{sin}) and a noise power level (\hat{P}_{noise}) are separately determined.
2. (Currently Amended) ~~A procedure in accord with Claim 1~~The process of claim 1,
~~therein characterized, in that~~wherein the level meter (3) ~~takes the samples of the output signals~~
(S_{out}) and determines a sample value~~in that,~~ from the sine power level, (\hat{P}_{sin}) by taking ~~the an~~
arithmetical average in device (33), of the samples and subsequent squaring (34) of the an amount
of the an arithmetical average of the samples (AVG), the sample value may be determined.
3. (Currently Amended) ~~The process of claim~~A procedure in accord with Claim 2,
~~wherein~~therein characterized, that the noise power level ~~is can be~~ obtained by taking ~~an the~~
arithmetical average (35) of the amount squared of the samples and subsequent subtraction of the
sine power level (\hat{P}_{sin}).
4. (Currently Amended) ~~The process of~~A procedure in accord with claim 2, wherein
~~or 3, therein characterized, in that~~ prior to taking the average value ~~(33, 35), an estimation (28)~~
~~and a revision (29) of a deviation of the frequency of the input sine signal (S_{in}) from the~~ the
frequency of an available local oscillator (22) in the level meter ~~are (3)~~ is carried out.
5. (Currently Amended) ~~The process of claim~~A procedure in accord with one of the
~~claims 1, wherein~~into 4, therein characterized, in that the magnitude of the noise is the noise
temperature T_{DUT} of the object to be measured~~2,~~ and the noise temperature T_{DUT} ~~is can be~~
determined by the formulae:

$$T_{DUT} = \frac{P_{sin}}{k \cdot B_M} \cdot \frac{P_{MESS,noise}}{P_{MESS,sin}}$$

whereby

P_{sin} is the power level of the sine signal at the input of the object to be measured (2)

$P_{MESS,sin}$ is the sine power level measured with the level meter (3)

$P_{MESS,noise}$ is the noise power level measured with the level meter (3)

k is the Boltzmann Constant, and

B_M is the bandwidth of the level meter (3).

are defined as they appear in the above equation.

6. (Currently Amended) ~~The process of claim A procedure in accord with one of the~~
~~claims 1, wherein: (a) to 4, therein characterized, in that, a calibration precedes the~~
~~measurement, in which the sine signal (S_{in}) has the same level identical to as is the case with~~
~~the measurement level; (b) the sine signal is input directly into the level meter, however,~~
~~circuitously by-passing the object to be measured; (2) the said sine signal (S_{in}) is input directly~~
~~into the level meter (3) and in that (c) the magnitude of the noise is the noise temperature T_{DUT} ,~~
and the noise temperature T_{DUT} of the object to be measured (2) is determined by the formula:

$$T_{DUT} = \frac{P_{sin}}{k \cdot B_M} \cdot \frac{(P_{MESS,noise} - P_{CAL,noise})}{P_{MESS,sin}}$$

wherein

P_{sin} is the power level of the sine signal at the input to the object to be measured (2),

$P_{MESS,sin}$ is the power level of the sine measured with intermediate circuitous inclusion of the object to be measured (2) and measured with the level meter (3)

$P_{MESS,Noise}$ is the power level of the noise measured with intermediate circuitous inclusion of the object to be measured (2) measured with the level meter (3)

$P_{\text{CAL,noise}}$ is the power level of the noise measured without intermediate circuitous inclusion of the object to be measured (2)-measured with the level meter (3)

k is the Boltzmann Constant

B_M is the bandwidth of the level meter-(3).

7. (Currently Amended) An apparatus for ~~determining the determination of~~ a magnitude of a noise (F_{OUT}) of an electronic object to be measured, (2) ~~with said apparatus comprising:~~

a sine-signal source ~~adapted to (1), which~~ produces a sine signal (S_{in}) which is to be input into the object to be measured; (2), and

~~a level meter (3) for measuring the measurement of~~ a power level at ~~an~~ the output of the object to be measured (2), ~~wherein therein characterized, in that~~ the level meter (3) is equipped with a sine power level detector device (31) for ~~the separately and discretely capturing of~~ a sine power level \hat{P}_{sin} and a noise power level detector device (32) for ~~the capturing of~~ a noise power level (\hat{P}_{noise}).

8. (Currently Amended) ~~The An~~ apparatus ~~of in accord with~~ claim 7, ~~wherein therein characterized, in that~~ the level meter (3) captures ~~the samples of an~~ the output signal (S_{out}) at the object to be measured (2) and ~~in that~~ the sine power level detector device (31) determines the sine-power level \hat{P}_{sin} by taking ~~the an~~ arithmetical average (33) of the samples and subsequent squaring (34) of ~~an the~~ amount of ~~an the~~ arithmetic average value (AVG) of the samples.

9. (Currently Amended) ~~The An~~ apparatus ~~of in accord with~~ claim 8, ~~wherein therein characterized, in that~~ the noise power level detector device (32) determines the noise power level (\hat{P}_{noise}) by taking ~~an the~~ arithmetical average (35) of ~~a the~~ square of ~~an the~~ amount of ~~a the~~ sample and subsequent subtraction (36) of the sine power level \hat{P}_{sin} .

10. (Currently Amended) ~~The An~~ apparatus ~~of in accord with~~ claim 8, ~~wherein 9, therein characterized in that~~ the level meter (3) has a frequency estimation device (28) which, prior to taking the average (33, 35) undertakes an estimation of a frequency deviation between

the frequency of the sine signal (S_{in}) input into the object to be measured, (2) and the frequency of a local oscillator (22) present in the level meter (3), and a frequency correction device (29), which rectifies the said frequency deviation.

11. (Currently Amended) ~~The~~ An apparatus of claim ~~in accord with one of the claims 7, wherein to 10, therein characterized, in that~~ the magnitude of the noise is the noise temperature T_{DUT} , and an evaluator (40) ~~is adapted to~~ determines the noise temperature T_{DUT} of the object to be measured ~~using by means of~~ the formula:

$$T_{DUT} = \frac{P_{sin}}{k \cdot B_M} \cdot \frac{(P_{MESS,noise})}{P_{MESS,sin}}$$

~~wherein the following symbols represent:~~

$P_{(sin)}$ is the power level of the sine signal at the input of the object to be measured (2),

$P_{(MESS,sin)}$ is the sine power level as measured with the level meter (3),

$P_{MESS,noise}$ is the noise power level as measured with the level meter (3),

k is the Boltzmann Constant, and

B_M is a ~~the~~ bandwidth of the level meter (3).

12. (Currently Amended) ~~The~~ An apparatus of claim ~~in accord with one of the claims 7, wherein to 11, therein characterized in that~~ (a) a calibration precedes the measurement, in the case of which the sine signal $P_{(sin)}$ is input directly into the level meter (3) ~~at the same level identical to a measurement level as determined by the measurement, however,~~ without an intermediate routing through the object to be measured; (2) ~~and in that~~ (b) the magnitude of the noise is the noise temperature T_{DUT} ; and (c) an evaluation device (40) ~~determines~~ the noise temperature T_{DUT} of the object to be measured in accord with the formula:

$$T_{DUT} = \frac{P_{sin}}{k \cdot B_M} \cdot \frac{(P_{MESS,noise} - P_{CAL,noise})}{P_{MESS,sin}}$$

~~wherein the following symbols represent:~~

P_{sin} is the power level of the sine signal at the

	input of the object to be measured-(2),	
$P_{\text{MESS},\text{sin}}$	<u>is</u> the sine power level with circuitous inclusion of the object to be measured (2)-as measured with the level meter-(3),	
$P_{\text{MESS},\text{noise}}$	<u>is</u> the noise power level with circuitous inclusion of the object to be measured -(2), as measured with the level meter-(3),	
$P_{\text{CAL},\text{noise}}$	<u>is</u> the noise power level without circuitous inclusion of the object to be measured -(2), as measured with the level meter-(3),	
k	<u>is</u> the Boltzmann Constant, and	
B_M	<u>is</u> at the bandwidth of the level meter-(3).	